


Modeling Relational Event Dynamics with statnet

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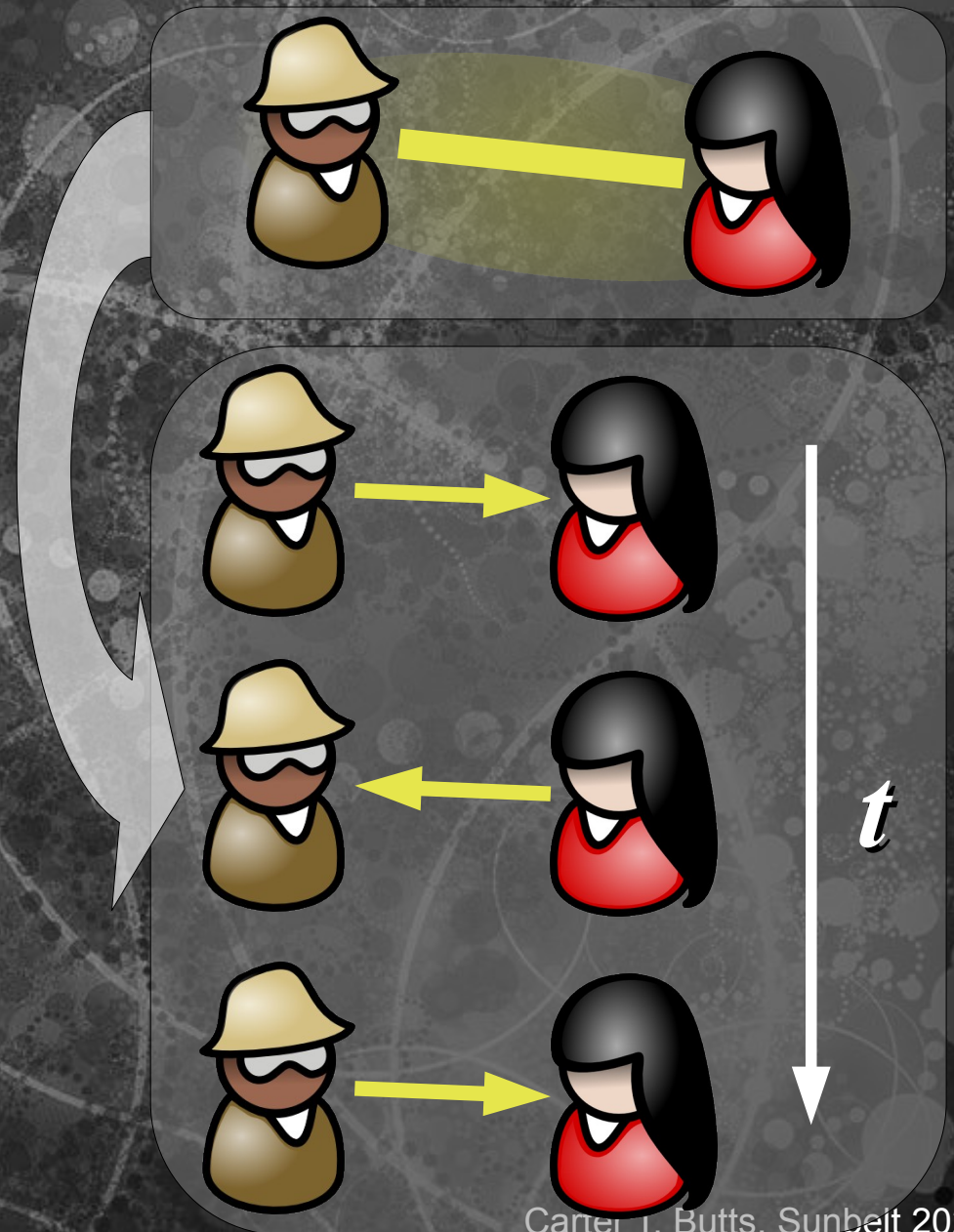
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Overview

- ◆ **Content in a nutshell**
 - ◆ Introduction to the use of relational event models (Butts, 2006; 2008) for the modeling interaction dynamics
 - ◆ Why this approach?
 - ◆ Fairly general
 - ◆ Principled basis for inference (estimation, model comparison, etc.) from actually existing data
 - ◆ Utilizes well-understood formalisms (event history analysis, multinomial logit)
- ◆ **This workshop:**
 - ◆ Introduction to modeling approach
 - ◆ Fitting dyadic relational event models
 - ◆ Model assessment and simulation

Unpacking Networks: From Relationships to Action

- ◆ Conventional network paradigm: focus on temporally extensive relationships
- ◆ Powerful approach, but not always ideal
- ◆ Sometimes, we are interested in the social action that lies beneath the relationships....



Actions and Relational Events

- ♦ **Action:** discrete event in which one entity emits a behavior directed at one or more entities in its environment
 - ♦ Useful "atomic unit" of human activity
 - ♦ Represent formally by relational events
- ♦ **Relational event:** $a=(i,j,k,t)$
 - ♦ $i \in \mathcal{S}$: "Sender" of event a ; $s(a)=i$
 - ♦ $j \in \mathcal{R}$: "Receiver" of event a ; $r(a)=j$
 - ♦ $k \in \mathcal{C}$: "Action type" ("category") for event a ; $c(a)=k$
 - ♦ $t \in \mathbb{R}$: "Time" of event a ; $\tau(a)=t$

Events in Context

- **Multiple actions form an event history,**
 $A_t = \{a_i : \tau(a_i) \leq t\}$
 - **Take $a_0 : \tau(a_0) = 0$ as "null action", $\tau(a_i) \geq 0$**
 - **Possible actions at t given by $\mathbf{A}(A_t) \subseteq \mathcal{S} \times \mathcal{R} \times \mathcal{C}$**
 - **Forms support for next action**
 - **Assume here that $\mathbf{A}(A_t)$ finite, constant between actions; may be fixed, but need not be**
- **Goal: model A_t**
 - **Treat actions as events in continuous time**
 - **Hazards depend upon past history, covariates**

Possible Events

Event Hazards

Time



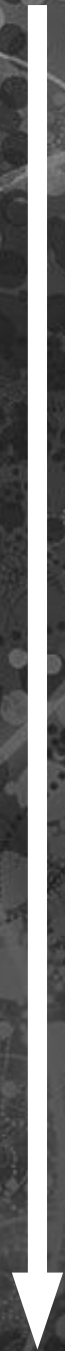
Possible Events

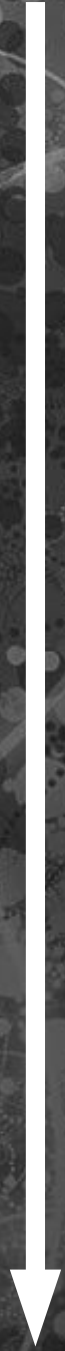
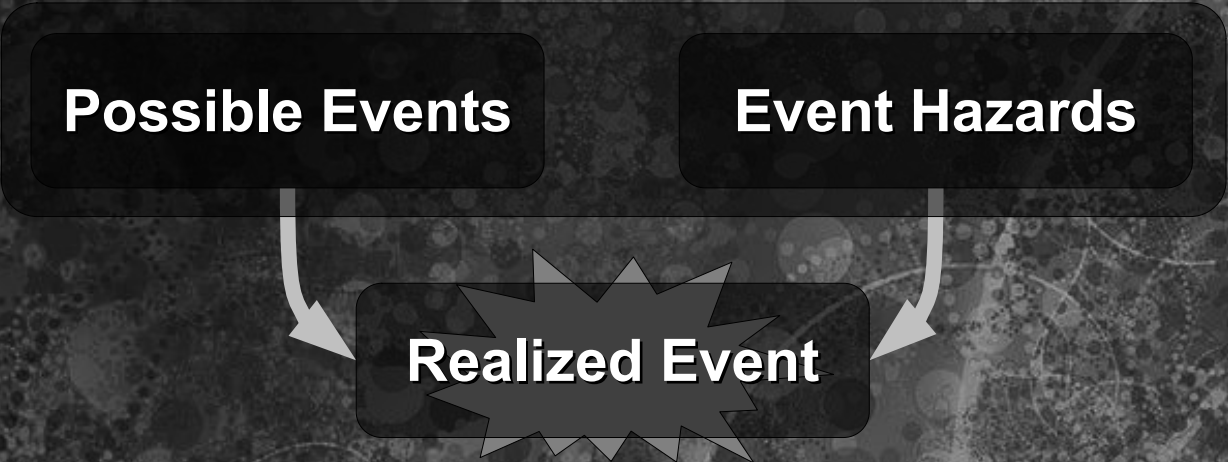
Event Hazards

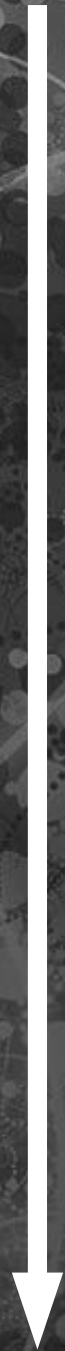
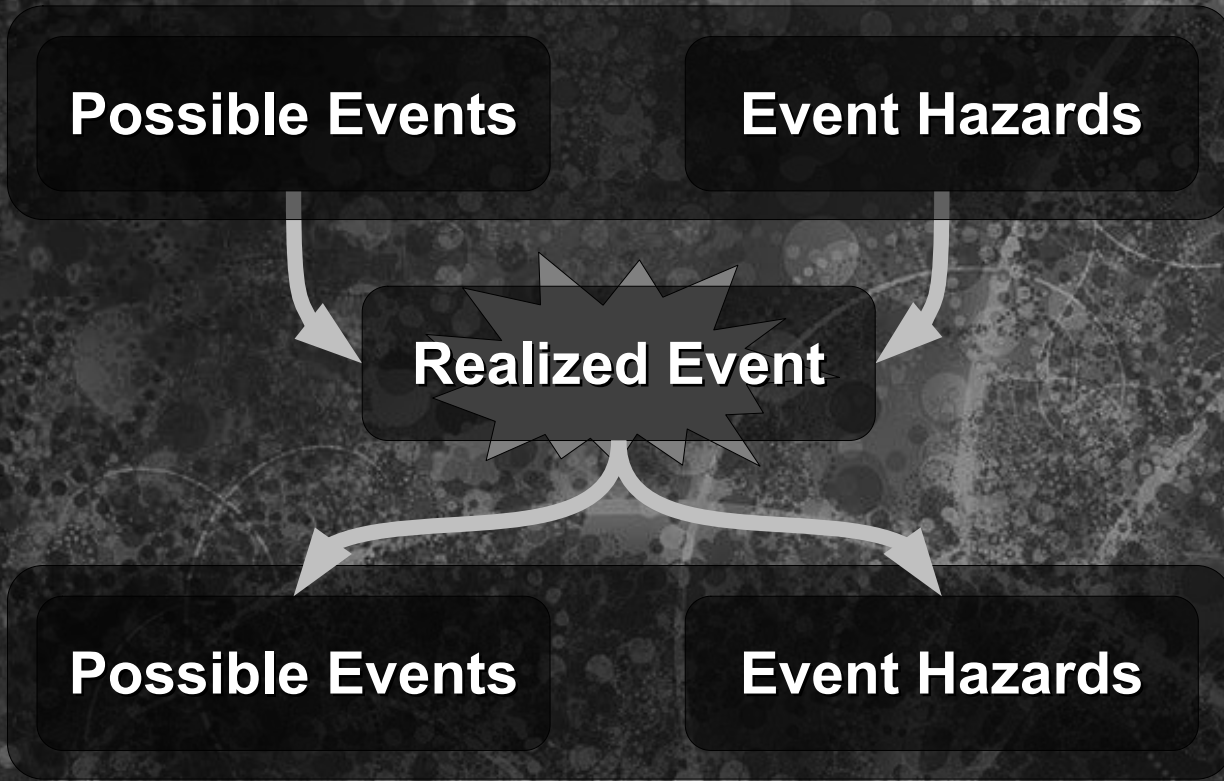
Context

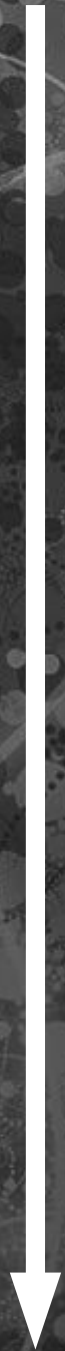
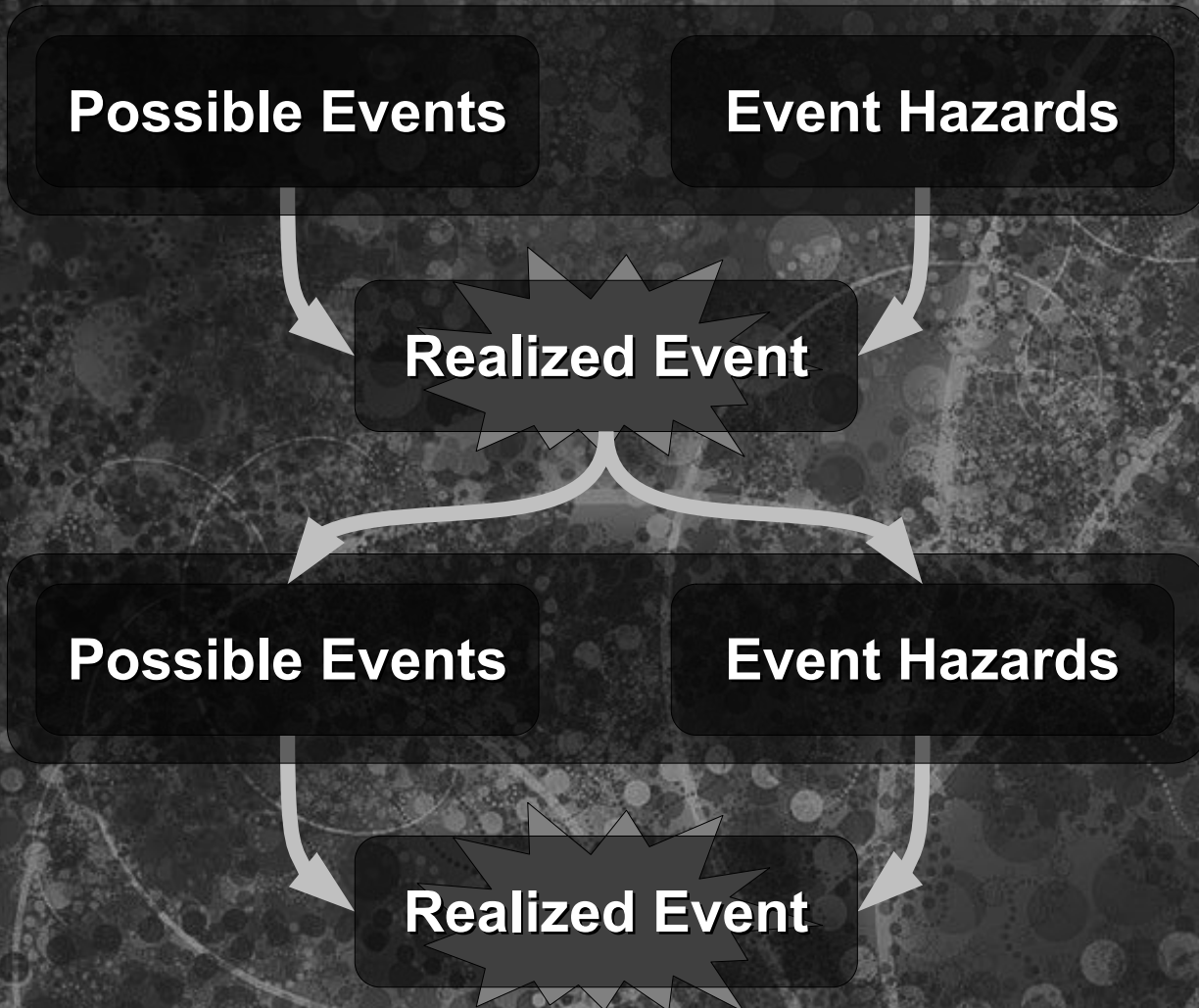


Time













Event Model Likelihood: Piecewise Exponential Case

- Natural simplifying assumption: actions arise as Poisson-like events with piecewise constant rates
 - Intuition: hazard of each possible event is *locally* constant, given complete event history up to that point
 - Waiting times conditionally exponentially distributed
 - Rates *can* change when events transpire, but not otherwise
 - Compare to related assumption in Cox prop. hazards model
 - Possible events likewise change only when something happens
- Can use to derive event likelihood
 - Let $M=|A_t|$, $\tau_i=\tau(a_i)$, w/hazard function $\lambda_{a_i A_k \theta} = \lambda(a_i, A_k, \theta)$; then

$$p(A_t | \theta) = \left[\prod_{i=1}^M \left(\lambda_{a_i A_{\tau_{i-1}} \theta} \prod_{a' \in A(A_{\tau_i})} \exp(-\lambda_{a' A_{\tau_{i-1}} \theta} [\tau_i - \tau_{i-1}]) \right) \right] \left[\prod_{a' \in A(A_t)} \exp(-\lambda_{a' A_t \theta} [t - \tau_M]) \right]$$

The Problem of Uncertain Event Timing

- ◆ Likelihood of an event sequence depends on the detailed history
 - ◆ Problem: exact timing is generally uncertain for many data sources (e.g., transcripts), though order is known
 - ◆ What if we only have (temporally) ordinal data?
- ◆ Stochastic process theory to the rescue!
 - ◆ Thm: Let X_1, \dots, X_n be independent exponential r.v. w/rate parameters $\lambda_1, \dots, \lambda_n$. Then the probability that $x_i = \min\{x_1, \dots, x_n\}$ is $\lambda_i / (\lambda_1 + \dots + \lambda_n)$.
 - ◆ Implication: likelihood of ordinal data is a product of multinomial likelihoods
 - ◆ Identifies rate function up to a constant factor

Event Model Likelihood: Ordinal Timing Case

- Using the above, we may write the likelihood of an event sequence A_t as follows:

$$p(A_t | \theta) = \prod_{i=1}^M \left[\frac{\lambda_{a_i A_{\tau_{i-1}}} \theta}{\sum_{a' \in A(A_{\tau_i})} \lambda_{a' A_{\tau_{i-1}}} \theta} \right]$$

- Dynamics governed by rate function, λ

$$\lambda_{a A_t, \theta} = \begin{cases} \exp(\lambda_0 + \theta^T u(s(a), r(a), c(a), A_t, X_a)) & a \in A(A_t) \\ 0 & a \notin A(A_t) \end{cases}$$

- Where λ_0 is an arbitrary constant, $\theta \in \mathbb{R}^p$ is a parameter vector, and $u: (i, j, A_p, X) \rightarrow \mathbb{R}^p$ is a vector of statistics

Interpreting the Parameters

- In general, each unit change in u_i multiplies the hazard of an associated event by $\exp(\theta_i)$
 - For ordinal time case, unit difference in u_i adds unit of θ_i to log odds of a vs a'
- Connection to multinomial choice models
 - Let $A_i(A_t)$ be the set of possible actions for sender i at time t . Then, conditional on no other event occurring before i acts, the probability that i 's next action is a is given by

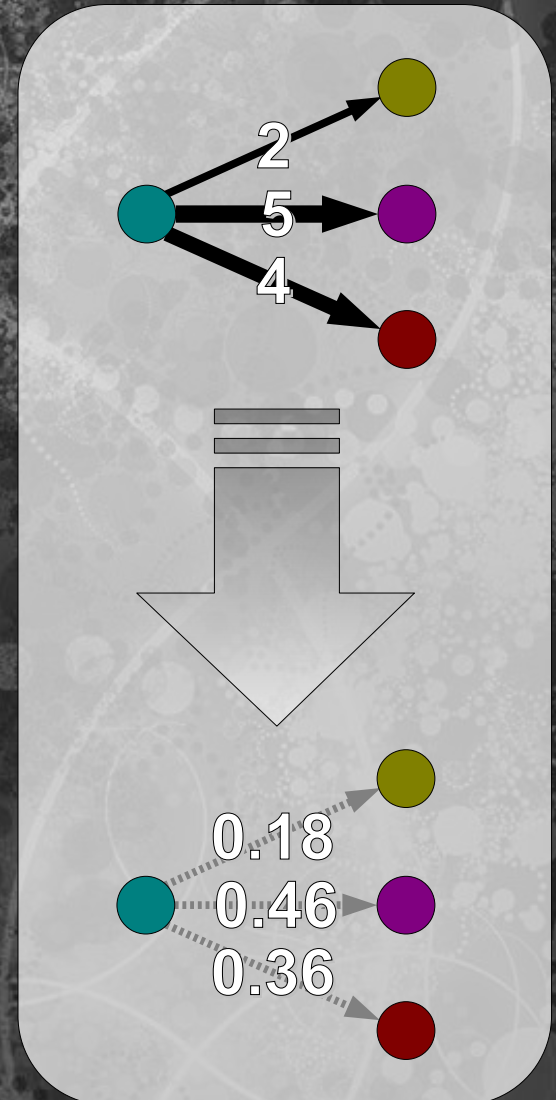
$$p(a|\theta) = \frac{\exp\left[\theta^T u(i, r(a), c(a), A_t, X_a)\right]}{\sum_{a' \in A_i(A_t)} \exp\left[\theta^T u(i, r(a'), c(a'), A_t, X_{a'})\right]}$$

Fitting Relational Event Models

- ◆ Given A_t and u , how do we estimate θ ?
 - ◆ Parameters interpretable as logged rate multipliers (in u)
- ◆ We have $p(A_t|\theta)$, so can conduct likelihood-based inference
 - ◆ Find MLE $\theta^* = \arg \max_{\theta} p(A_t|\theta)$, e.g., using a variant Newton-Rapheson or other method
 - ◆ Can also proceed in a Bayesian manner
 - ◆ Posit $p(\theta)$, work with $p(\theta|A_t) \propto p(A_t|\theta)p(\theta)$
 - ◆ Some computational challenges when $|A|$ is large; tricks like MC quadrature needed to deal with sum of rates across support

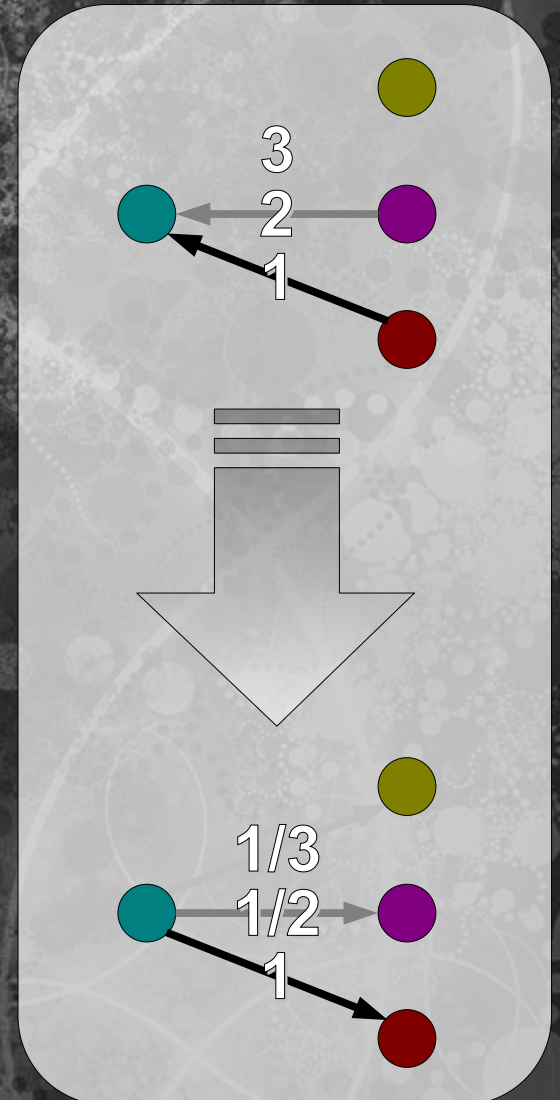
Persistence Effects

- ◆ Inertia-like effect: past contacts may tend to become future contacts
 - ◆ Unobserved relational heterogeneity
 - ◆ Availability to memory
 - ◆ (Compare w/autocorrelation terms in an AR process)
- ◆ Simple implementation: fraction of previous contacts as predictor
 - ◆ Log-rate of (i,j) contact adjusted by $\theta d_{ij}/d_i$



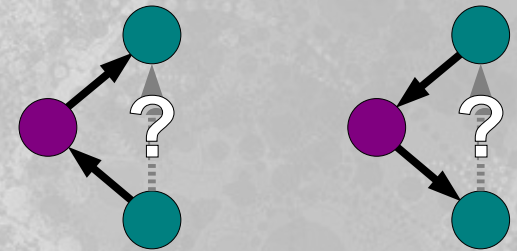
Recency/Ordering Effects

- ◆ Ordering of past contact potentially affects future contact
 - ◆ Reciprocity norms
 - ◆ Recency effects (salience)
- ◆ Simple parameterization: dyadic contact ordering effect
 - ◆ Previous incoming contacts ranked
 - ◆ Non-contacts treated as rank ∞
 - ◆ Log-rate of outgoing (i,j) contact adjusted by $\theta(1/\text{rank}_{ji})$



Triadic/Clustering Effects

- Can also control for endogenous triadic mechanisms
 - Two-path effects
 - Past outbound two-path flows lead to/inhibit direct contact (transitivity)
 - Past inbound two-path flows lead to/inhibit direct contact (cyclicity)
 - Shared partner effects
 - Past outbound shared partners lead to/inhibit direct contact (common reference)
 - Past inbound shared partners lead to/inhibit direct contact (common contact)



Two-Path Effects

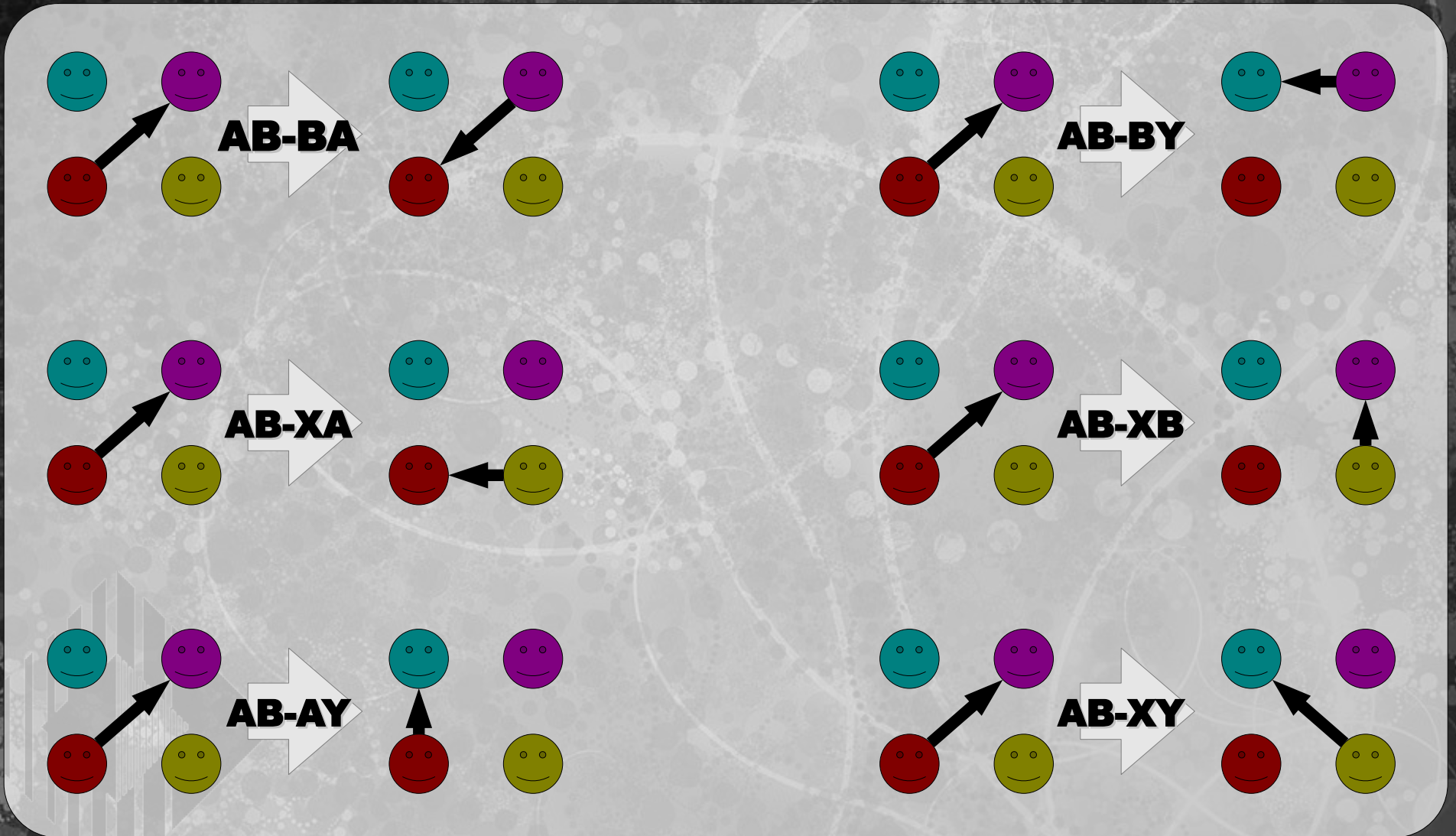


Shared Partner Effects

Participation Shifts

- ◆ **Proposal of Gibson (2003) for studying conversational dynamics**
 - ◆ Classify actors into *senders*, *receivers*, and *bystanders*
 - ◆ When roles change, a *participation shift* ("P-shift") is said to occur
 - ◆ Study conversational dynamics by examining the incidence of P-shifts
- ◆ **P-shift typology**
 - ◆ For dyadic communication, 6 possible P-shifts; allowing indefinite targets expands set to 13
 - ◆ Can compute observed, potential shifts given an event sequence

Dyadic P-Shifts, Illustrated



Preferential Attachment

- ◆ Past interactive activity affects tendency to receive action
 - ◆ E.g., emergent coordination roles
 - ◆ Exposure-based saliency ("who's out there?")
 - ◆ Practice/specialization (efficiency)
- ◆ Implement via past total degree effect on hazard of receipt
 - ◆ Fraction of all past calls due to i as effect for all j to i events

